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AN INVARIANT MEASURE FOR THE

EQUATION $u_{tt} - u_{xx} + u^3 = 0$

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ABSTRACT

Numerical studies of the initial boundary-value problem for the semilinear wave equation

 $u_{tt} - u_{xx} + u^3 = 0$

subject to periodic boundary conditions $u(t,0) = u(t,2\pi)$, $u_t(t,0) = u_t(t,2\pi)$ and initial conditions $u(0,x) = u_0(x)$, $u_t(0,x) = v_0(x)$, where $u_0(x)$ and $v_0(x)$ satisfy the same periodic conditions, suggest that solutions ultimately return to a neighborhood of the initial state $u_0(x)$, $v_0(x)$ after undergoing a possibly chaotic evolution.

In this paper, an appropriate abstract space is considered. In this space a finite measure is constructed. This measure is invariant under the flow generated by the Hamiltonian system which corresponds to the original equation. This enables one to verify the above returning property.

AMS (MOS) Subject Classifications: 35L70, 28D05, 58F11

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AN INVARIANT MEASURE FOR THE EQUATION $u_{tt} - u_{xx} + u^3 = 0$

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0. Introduction

During the Sixth I. G. Petrovskii memorial meeting of the Moscow Mathematical Society in January 1983 Professor V. B. Zakharov proposed the following problem. Numerical experiments demonstrated that the equation

$$(0.1) u_{++} - u_{xx} + u^3 = 0$$

with periodic boundary conditions $u(t,0) = u(t,2\pi)$, $u_t(t,0) = u_t(t,2\pi)$ possesses the "returning" property, i.e. solutions appear to be very close to the initial state $u(0,x) = u_0(x)$, $u_t(0,x) = v_0(x)$, where the initial functions satisfy the above boundary conditions, after some time of rather chaotic evolution. The problem is to explain this phenomenon. According to the classical Poincaré theorem every flow which preserves a finite measure has the returning property modulo a set of measure zero. The aim of this paper is to build such a measure for the flow

$$\phi(t)(u_0(x), v_0(x)) = (u(t,x), v(t,x))$$
,

where u(t,x) is the solution of (0.1), $v(t,x) = u_t(t,x)$, where the solution u satisfies the initial data $u(0,x) = u_0(x)$, $u_t(0,x) = v_0(x)$. The equation (0.1) can be rewritten as a Hamiltonian system

$$\begin{cases} u_{t} = \delta H/\delta v \\ v_{t} = -\delta H/\delta u \end{cases}$$

with the Hamiltonian

(0.3)
$$R(u,v) = \int_0^{2\pi} (v^2/2 + u_x^2/2 + u^4/4) dx .$$

Our starting point is the desired formula

(0.4)
$$\int F(u,v)d\mu(u,v) = \int F(u,v)e^{-H(u,v)} \pi du(x)dv(x)$$

for some class of "good" functionals F.

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The right-hand side of (0.4) is the partition function. It can be determined by finite dimensional approximations (2.3). Roughly speaking the measure du is the "canonical symplectic measure" I dudy multiplied by the function e^{-H} of the Hamiltonian and is invariant under the flow (0.2). However, the correct definition of the du involves some technical problems and the expression II dudy does not have any meaning without the factor e^{-H}. The Hamiltonian H is the sum of

$$H_1(u) = \int_0^{2\pi} (u_x^2/2 + u^4/4) dx$$
 and $H_2(v) = \int_0^{2\pi} (v^2/2) dx$,

so the measure du is the Cartesian product of the measures

$$d\mu_1 = e \qquad \text{if } du(x) \quad \text{and} \quad d\mu_2 = e \qquad \text{if } dv(x) \quad .$$

The $d\mu_1$ is correctly defined by finite dimensional distributions $p(x_1,\dots,x_k;\xi_1,\dots,\xi_k)$:

$$d\mu_4\{u(x): (u(x_4),...,u(x_k)) \in M\} = \int_M p(x,\xi)d\xi$$

which are proportional to partition functions

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(0.5)
$$\begin{cases} \xi_j = u(x_j)^e \end{cases}$$

which are calculated in Section 2. In order to formulate the result we introduce some notation. Let x < y be two real numbers. $U(x,\xi_1y,\eta_1z)$ is the solution of the equation $U_{XX} = U^3$ in the segment [x,y] with the boundary conditions $U(x) = \xi$, $U(y) = \eta$. Let

$$h_4(x,\xi_1y,\eta) = \int_0^y [U_2^2(x,\xi_1y,\eta_1z)/2 + U^4(x,\xi_1y,\eta_1z)/4]dz =$$

$$\min\{\int_{u}^{y}(u_{-}^{2}/2 + u^{4}/4)dx \mid u(x) = \xi, u(y) = \eta\}$$

and let $D(x,\lambda_j y,\eta)$ be the regularized determinant of the operator, see [4],

$$(0.6) - d^2/dx^2 + 3v^2(x,\xi_1y,\eta_1z) ,$$

in the segment [x,y] with the Dirichlet boundary conditions. The operator (0.6) is the operator of second variation of the functional

$$\int_{X}^{y} (u_{z}^{2}/2 + u^{4}/4) dz \; ; \; u(x) = \xi, \; u(y) = \eta$$

in the neighborhood of the extremum U. Then

(0.7)
$$p(x,\xi) = \frac{c(x)}{\sqrt{\|D(x_{1},\xi_{1};x_{1+1},\xi_{1+1})}} \exp\{-\sum_{j=1}^{\infty} (x_{j},\xi_{j};x_{j+1},\xi_{j+1})\}$$

The function c is determined from the condition

and is equal to

(6.8)
$$\sigma(2\pi)^{-k/2} \ \Pi_{j=1}^{k} (\pi_{j+1} - \pi_{j})^{-1/2}$$

with some constant σ . The measure $d\mu_1$ is absolutely continuous with respect to the classical Wiener measure; so its support belongs to the space Lip^G , $0 < \alpha < 1/2$. After replacing the functional $\pi_1(u)$ with $\int (u_X^2/2) dx$ the construction will lead us exactly to the classical Wiener measure. The $d\mu_2$ is a realisation of the abstract Wiener measure and it will be described in Section 3.

In Section 1 we investigate the determinant of the operator (0.6). In particular we prove the formula

(6.9)
$$\det(\Delta_o^{-1} + F(x)) = \det(\Delta_o)\det(I + \Delta_o^{-1}F(x)) ,$$

where Δ_O is the operator $-d^2/dx^2$ with the Dirichlet boundary conditions and F(x) is a nonnegative smooth function. The determinants of $\Delta_O + F(x)$ and Δ_O are equal to $\exp(-\zeta^*(0))$, where $\zeta(x)$ is the ζ - function of an operator; $\det(I + \Delta_O^{-1}F(x))$ is well defined because the operator Δ_O^{-1} is nuclear, $\Delta_O^{-1}F \in \gamma_1$. The formula (0.9) is not used in our constructions but we think it is interesting by itself. In Section 2 we calculate the partition function (0.5), in Section 3 we give the correct definition of the measure Δ_O and finally in Section 4 we prove the main result:

Theorem. The measure dy is invariant under the flow (0.2).

I. The determinant of the Sturm-Liouville operator with the Dirichlet conditions.

We investigate properties of the functional determinants by finite dimensional approximations. The key lemma is

Lemma 1. Let $F(x) \in C^0(0,a)$, $\rho > 0$, and let Δ_0 be the operator $-d^2/dx^2$ with the Dirichlet conditions. Consider $(W-1) \times (W-1)$ matrices

$$\delta_{N} = \frac{N^{2}}{a^{2}} \begin{bmatrix} 2 & -1 & 0 & \dots & 0 \\ -1 & 2 & -1 & \dots & 0 \\ \dots & \dots & \dots & \dots & \dots \\ 0 & 0 & \dots & -1 & 2 \end{bmatrix} \quad \text{and} \quad f_{N} = \|f_{N;i,j}\| \quad ,$$

where

$$f_{N,ij} = \begin{cases} \alpha F(j/N) + r_{jj}^{(N)} & \text{if } i = j \\ \beta F(j/N) + r_{j+1,j}^{(N)} & \text{if } i = j+1 \\ \\ \beta F((j-1)/N) = r_{j-1,j}^{(N)} & \text{if } i = j-1 \\ \\ 0 & \text{if } |i-j| > 1 \end{cases}$$

 $\alpha + 2\beta = 1$ and

$$\lim_{N\to\infty}\max_{i,j}|r_{ij}^{(N)}|=0.$$

Then

$$\det(\mathbf{I} + \Delta_{\mathbf{O}}^{-1}\mathbf{F}) = \lim_{\mathbf{N} \to \mathbf{O}} \det(\mathbf{I} + \delta_{\mathbf{N}}^{-1}\mathbf{f}_{\mathbf{N}}) .$$

Proof. Consider the orthonormal basis $E_k(x)=\sqrt{2/a}\sin(\pi kx/a)$ of the eigenfunctions of the operator $\Delta_o:\Delta_oE_k=\lambda_kE_k$ with $\lambda_k=\pi^2k^2/a^2$, $k=1,2,\ldots$. Denote by H_a^B the scale of Sobolev spaces which are generated by $\Delta_o^{-1/2}:E_k(x)E_g=\lambda_k^{g/2}$. The operator δ_N is defined on C^{N-1} ; its eigenvalues

$$\lambda_{k}^{(N)} = \frac{4N^{2}}{s^{2}} \sin^{2} \frac{\pi k}{2N}, k = 1, ..., N-1$$

the corresponding eigenvectors

$$e_k^{(N)} = (e_{k1}^{(N)}, \dots e_{k-N-1}^{(N)})$$
 with $e_{ks}^{(N)} = \sqrt{2/a} \sin(\pi ks/N), k,s = 1, \dots, N-1$.

We normalize o(N) by the condition

$$|e_k^{(N)}|^2 = \frac{a}{N} \sum_{n=1}^{N-1} |e_{kn}^{(N)}|^2 = 1$$
.

Let t_N^2 be the space \mathbf{c}^{N-1} with the norm $|\cdot|$ and let \mathbf{h}_N^S be the same space with the norm $|\mathbf{y}|_S = |\delta_N^{S/2}\mathbf{y}|$. Now we introduce the interpolation operator $\mathbf{i}_N : t_N^2 + \mathbf{L}^2[0,a]$ and the restriction operator $\mathbf{j}_N : \mathbf{L}^2[0,a] + t_N^2$:

$$i_{N}e_{k}^{(N)} = E_{k}(x), k = 1,...,N-1 ,$$

$$j_{N}E_{k}(x) = \begin{cases} e_{k}^{(N)} & \text{if } k = 1,...,N-1 \\ 0 & \text{if } k \ge N \end{cases} .$$

We split the segment [0,a] into N equal parts by the points $0 = x_0 < x_1 < \cdots < x_{N-1} < x_N = a$, $x_j = ja/N$. The i_N is the operator of trigonometrical interpolation of the values at x_j , $j_N = x_N p_N$, where p_N is the ortho-projector onto the subspace spanned by x_1, \dots, x_{N-1} and

$$r_{M}G = (G(a/N), ..., G((N-1)a/N))$$
.

First of all we notice that the norms of i_N and j_N as operators which map h_N^g into H_0^g and H_0^g onto h_N^g correspondingly are bounded by constants which do not depend on M because

$$1 < \lambda_k/\lambda_k^{(N)} = (\pi k/2N)^2/\sin^2(\pi k/2N) < \pi^2/4$$
, $k = 1,...,M-1$.

Consider the finite-dimensional operator

$$T_N = i_N \delta_N^{-1} f_N j_N : L^2[0,a] + L^2[0,a]$$

Clearly

$$\det(\mathbf{I}+\mathbf{T}_{\mathbf{N}}) = \det(\mathbf{I}+\delta_{\mathbf{n}}^{-1}\mathbf{f}_{\mathbf{N}}) .$$

So the convergence of T_N to $T = \Delta_0^{-1}F$ in the space Y_1 of nuclear operators implies the assertion of the lemma, see [5]. We split the proof of convergence into the following steps. The operators

- (i) T_H are uniformly bounded in the space $L(L^2, H_0^8)$ of linear operators $L^2 + H_0^8$.
- (ii) $T_N + T$ in the space $L_g(L^2, L^2)$ with the strong topology. Let ϕ be a trigonometrical polynomial. Then

$$\begin{array}{lll} \mathbf{T}_{N}\phi & -\mathbf{T}\phi & = \mathbf{i}_{N}\delta_{N}^{-1}[\mathbf{f}_{N}\mathbf{j}_{N} & -\mathbf{j}_{N}\mathbf{F}(\mathbf{x})]\phi & + \mathbf{i}_{N}\delta_{N}^{-1}\mathbf{j}_{N}(\mathbf{I}-\mathbf{P}_{k})\mathbf{F}(\mathbf{x})\phi \\ & + (\mathbf{i}_{N}\delta_{N}^{-1}\mathbf{j}_{N} & -\Delta_{O}^{-1})\mathbf{P}_{k}\mathbf{F}(\mathbf{x})\phi & -\Delta_{O}^{-1}(\mathbf{I}-\mathbf{P}_{k})\mathbf{F}(\mathbf{x})\phi & + \end{array}$$

The second and the fourth terms on the right hand side of (I.I) converge to 0 uniformly

with respect to W when $k + \infty$. Operators $(i_{\rm H} \delta_{\rm H}^{-1} j_{\rm H} - \Delta_{\rm O}^{-1}) P_{\rm K}$ have orthonormal basis of eigenfunctions $E_4(x)$. The corresponding eigenvalues are equal to

$$a^2/(4N^2\sin^2(\pi j/2N)) - a^2/(\pi^2j^2) \xrightarrow{N+\infty} 0 \text{ if } j < k-1 \text{ and } 0 \text{ if } j > k$$

therefore the third term in (I-I) converges to 0 when $N+\infty$ and k is fixed. Let

$$[f_{H}r_{H} - r_{H}F(x)]\phi(x) = (y_{1}^{(N)}, \dots, y_{N-1}^{(N)})$$
.

Then

$$\begin{split} y_{j}^{(N)} &= \beta F((j-1)a/N)\phi((j-1)a/N) + x_{j,j-1}^{(N)}\phi((j-1)a/N) \\ &+ \alpha F(ja/N)\phi(ja/N) + x_{j,j}^{(N)}\phi(ja/N) + \beta F(ja/N)\phi((j+1)a/N) \\ &+ x_{j,j+1}^{(N)}\phi((j+1)a/N) - F(ja/N)\phi(ja/N) \end{split}$$

and $\lim_{N\to\infty} \max_j |y_j^{(N)}| = 0$. Thus $|(f_N r_N - r_N F)| + 0$ in k_N^2 . Further, $(r_N - j_N)F\phi + 0$ when $N+\infty$ and $r_N\phi = j_N\phi$ if N is sufficiently large. So the first term on the right hand side of (I.I) converges to 0 when $N+\infty$. Combining the results above we obtain that $T_N\phi + T\phi$. The set of T_N is bounded and trigonometrical polynomials are dense in L^2 ; hence $T_N + T$ in strong topology.

(iii) $T_{\rm H}$ + T in the space $L_{\rm g}(L^2,H_{\rm e}^2)$, by virtue of (i), (ii) and Banach-Steinhaus theorem.

(iv) $T_H + T$ in the space $L(H_e^S, H_e^2)$, s > 0, by virtue of (iii) and the compactness of the imbedding $H_e^S \hookrightarrow L^2$.

The space $L(H_n^g,H_n^2)$ belongs to $Y_1(H_n^g)$ when s<1, see [6]. Hence T_N+T in $Y_1(H_n^g)$, 0< s<1.

Lemma 2. Let $F(x) \in C^2[0,a]$ and let A(x) be the solution of the equation $A^{**}(x) = F(x)A(x)$

with the boundary conditions

$$A(a) = 0, A^{\dagger}(a) = -Wa ,$$

where $A_{\nu}^{(N)}$, ν = 0,1,...,N, N = 2,3,..., satisfies the difference equation $(N^2/a^2)(A_{\nu+1}^{(N)}-2A_{\nu}^{(N)}+A_{\nu-1}^{(N)})=F((N-\nu)a/N)$

with

$$A_0^{(N)} = 0, A_1^{(N)} = H/H$$
.

Then

$$A(0) = \lim_{N \to \infty} A_N^{(N)} .$$

Proof. Let
$$R_{\nu}^{(N)} = \lambda_{\nu}^{(N)} - \lambda((N-\nu)a/N)$$
 and $C_{\nu}^{(N)} = R_{\nu}^{(N)} - R_{\nu-1}^{(N)}$. Then (I.2) $(N^2/a^2)(R_{\nu+1}^{(N)} - 2R_{\nu}^{(N)} + R_{\nu-1}^{(N)}) = F((N-\nu)a/N)R_{\nu}^{(N)} + b_{\nu}^{(N)}$

and

(I.2')
$$(N^2/a^2)(C_{\nu+1}^{(N)} - C_{\nu}^{(N)}) = F((N-\nu)a/N) \sum_{j=1}^{\nu} C_{j}^{(N)} + b_{\nu}^{(N)}$$

with $R_0^{(N)}=0$, $R_1^{(N)}=C_1^{(N)}+O(N^{-3})$ and $b_v^{(N)}=0(N^{-2})$ uniformly with respect to v. Clearly $C_v^{(N)}$ are bounded by the solutions of the equation of the type (I.2') with F((N-v)a/N), $b_v^{(N)}$ and $C_1^{(N)}$ replaced by $C_1=\sup|F(x)|$, C_2/N^2 and C_3/N^3 respectively. Hence $R_v^{(N)}$ are bounded by the solution of the following difference equation $(N^2/a^2)(x_{v+1}^{(N)}-x_v^{(N)}+x_{v+1}^{(N)})=C_1x^{(N)}+C_2/N^2; \ x_0^{(N)}=0, \ x_1^{(N)}=C_3/N^2 \ .$

The general solution of this equation is

$$x_{v}^{(\mathrm{N})} = -c_{2}/(c_{1}^{\mathrm{N}^{2}}) + \alpha^{(\mathrm{N})} [\lambda_{+}^{(\mathrm{N})}]^{v} + \beta^{(\mathrm{N})} [\lambda_{-}^{(\mathrm{N})}]^{v}$$

with $\lambda_{\pm}^{(N)}=1\pm C_4/N+\dots$ and $\lambda_{+}^{(N)}\lambda_{-}^{(N)}=1$. According to the initial conditions $\alpha^{(N)}+\beta^{(N)}=C_5/N^2, \ \alpha^{(N)}\lambda_{+}^{(N)}+\beta^{(N)}\lambda_{-}^{(N)}=C_3/N^2 \ .$

Hence

$$\alpha^{(N)} = ((c_3 \lambda_+^{(N)})/N^3 - c_5/N^2)/(\lambda_+^{(N)^2} - 1) = 0(N^{-1}), \beta^{(N)} = 0(N^{-1}).$$

Therefore

$$r_N^{(N)} \le c_5/N^2 + c_6(I+c_7/N)^N/N \le c_8/N$$
 and $R_N^{(N)} = O(N^{-1})$.

Theorem 1. Let $F(x) \in C^2[0,a]$ and let A(x) be the solution of the equation $A^{r,r}(x) = F(x)A(x)$

with the boundary conditions

$$\lambda(a) = 0$$
, $\lambda^{\dagger}(a) = -I/a$.

Then

$$\det(\mathbf{I} + \Delta_0^{-1} \mathbf{F}) = \lambda(0) .$$

Proof. Let $f_{\mathbb{N}} = \text{diag}(P(a/N), \dots, P((N-1)a/N))$ be the diagonal matrix. By Lemma 1

$$\det(\mathbf{I}+\delta_{\mathbf{N}}^{-1}\mathbf{F}) = \lim_{\mathbf{N}\to\infty} \det(\mathbf{I}+\delta_{\mathbf{N}}^{-1}\mathbf{f}_{\mathbf{N}})$$

Above we have used the relation

which can be proved easily.

By elementary transformations the matrix D_{ij} can be transformed into

with

(I.3)
$$v_j = 2 + a^2 F(ja/N)/N^2 - 1/v_{j-1}, v_1 = 2 + a^2 F(a/N)/N^2$$

Our aim is to find N-1v1...vn-1. Let

$$H^{-1}v_{H-V}\cdots v_{H-1} = A^{(H)}v_{H-V} + B^{(H)}, A_1^{(H)} = H^{-1}, B_1^{(N)} = 0$$

It follows from (I.3) that

$$(H^2/a^2)(A_{\nu+1}^{(N)} - 2A_{\nu}^{(N)} + A_{\nu-1}^{(N)}) = F((H-\nu)a/H)A^{(N)}$$

 $A_{\nu}^{(N)} = 0, A_{1}^{(N)} = I/N$.

The value

$$N^{-1} \det D_{N} = A_{N-1}^{(N)} V_{1} + B_{N-1}^{(N)} = A_{N}^{(N)}$$

converges to A(0) when N + * by Lemma 2. The theorem is proved.

Now we shall prove the formula (0.9). Let us remind the definition of the determinant of a positive unbounded operator λ . Assume that $\lambda^{-\sigma} \in \Upsilon_1$ for some positive σ . One can define the function

$$\zeta_{\lambda}(z) = \text{Tr}(\lambda^{-2})$$

which is regular in the helf-plane $Rez > \sigma$. In some cases (e.g. if A is a pseudo-differential operator) this function has the meromorphic continuation. It may happen that 0 is a regular point of this ζ - function. In this case we say that A has a determinant and

$$\det A = \exp(-\zeta_2^*(0)) .$$

This definition is a generalization of the finite-dimensional determinant.

Theorem 2. Let $S > c_0 > 0$ be a positive operator in a separable Hilbert space H, let $S^{-\sigma} \in \gamma_1$ for some σ , $0 < \sigma < 1$ and det S be defined. Let T be a bounded operator. Then there exists a constant C which depends upon c_0 and TT only, such that det $A(\varepsilon) = \det(S+\varepsilon T)$ is defined when $|\varepsilon| < C$ and is equal to det S det $(T+\varepsilon S^{-1}T)$.

Proof. One has the following integral representation on the strip 0 < Res < 1, see [7]:

$$A^{-z}(\varepsilon) = \frac{\sin \pi z}{\pi} \int_0^{\infty} e^{-z} (\varepsilon I + \lambda(\varepsilon))^{-1} d\varepsilon$$

$$= s^{-z} + \frac{\sin \pi z}{\pi} \int_0^{\infty} e^{-z} \sum_{k=1}^{\infty} (-1)^k \varepsilon^k [(\varepsilon I + S)^{-1} T]^k (\varepsilon I + S)^{-1} d\varepsilon .$$

If $\varepsilon < c_{o}/\text{ITI}$ we can change the order of summation and integration:

Let us show that all terms on the right hand side of (I.4) are nuclear operators and estimate their γ_1 - norms which will be denoted by $|||\cdot|||$. One has

$$\begin{split} & |||[(\mathtt{ti+s})^{-1}\mathtt{T}]^k(\mathtt{ti+s})^{-1}||| < |||s^{-\sigma}||| \cdot ||[(\mathtt{ti+s})^{-1}\mathtt{T}]^k(\mathtt{ti+s})^{-1}s^{\sigma}|| \\ & < |||s^{-\sigma}||| \cdot ||\mathtt{Ti}|^k(\mathtt{t+c}_o)^{-k} \left\{ \begin{matrix} \sigma^{\sigma}(1-\sigma)^{1-\sigma}\mathtt{t}^{\sigma-1} & \text{if } \mathbf{t} > c_o(1-\sigma)/\sigma \\ \\ c_o^{\sigma}/(\mathtt{t+c}_o) & \text{if } \mathbf{t} < c_0(1-\sigma)/\sigma \end{matrix} \right. \end{split}$$

Therefore

$$\begin{split} ||||_0^\infty \ t^{-z} (t I + s)^{-1} T^k (t I + s)^{-1} dt ||| \\ & \leq |||s^{-\sigma}||| \cdot \|TI^k \{ (1 - \sigma) \sigma^{-1} (1 - Rez)^{-1} c_o^{-k + \sigma + 1 - Rez} \\ & + \sigma^{\sigma} (1 - \sigma)^{1 - \sigma} (Rez + k - \sigma)^{-1} c_o^{-k + \sigma - Rez} \} \end{split} .$$

Thus the series (I.4) is γ_1 - convergent when $\epsilon < c_0/\text{ITI}$ and it defines the γ_1 - valued regular function on the strip σ -1 < Rez < 1. Hence $\zeta_{A(\epsilon)}(z)$ has the meromorphic extension to the half-plane Rez > σ -1 and 0 is a regular point of this function:

$$\zeta_{A(\epsilon)}^{\prime}(0) - \zeta_{S}^{\prime}(0) = \Sigma_{k=1}^{\infty}(-1)^{k}\epsilon^{k} \int_{0}^{\infty} Tr\{\{(tI+S)^{-1}T\}^{k}(tI+S)^{-1}\}dt$$
.

Note that

$$\frac{d}{dt} [(tI+s)^{-1}T]^{k} = -\sum_{i=0}^{k-1} [(tI+s)^{-1}T]^{i} (tI+s)^{-1} [(tI+s)^{-1}T]^{k-i}.$$

Hence

$$Tr\{[(tI+S)^{-1}T]^k(tI+S)^{-1}\} = -\frac{1}{k}\frac{d}{dt}Tr\{(tI+S)^{-1}T\}^k$$

and

$$\begin{split} \zeta_{A(\epsilon)}^{*}(0) &- \zeta_{S}^{*}(0) = \Sigma_{k=1}^{\infty} (-1)^{k+1} \frac{\epsilon^{k}}{k} \int_{0}^{\infty} \frac{d}{dt} \operatorname{Tr} \{ (tI+S)^{-1}T \}^{k} dt \\ &= \Sigma_{k=1}^{\infty} (-1)^{k} \epsilon^{k} k^{-1} \operatorname{Tr} (S^{-1}T)^{k} = -\operatorname{Tr} \log (I+\epsilon S^{-1}T) \end{split}.$$

Thus

$$\det A(\varepsilon)/\det S = \exp\{-\left[\zeta_{A(\varepsilon)}^{i}(0) - \zeta_{S}^{i}(0)\right]\} = \exp \operatorname{Tr} \log(I + \varepsilon S^{-1}T)$$
$$= \det(I + \varepsilon S^{-1}T) .$$

Corollary. Let S be the same operator as in Theorem 2 and let T be a non-negative bounded operator. Then det(S+T) is defined and

$$det(S+T) = det S det(I+S^{-1}T)$$

Proof. Note that S+ET > c_0 for every E > 0. So we can apply Theorem 2 N times if N is sufficiently large and obtain

$$\det(s+\tau) \; = \; \det \; s \quad \mathbb{R}^{n-1}_{j=0} \; \det(\mathtt{I}+\mathtt{M}^{-1}(s+j\mathtt{M}^{-1}\tau)^{-1}\tau) \quad .$$

The product $\, \mathbb{I} \,$ in the last formula is equal to the $\det(\mathbb{I} + \mathbb{B}^{-1} \mathbb{T})$, as follows from the identity

(I.5)
$$\det(I+\varepsilon_1S^{-1}T)\det(I+\varepsilon_2(S+\varepsilon_1T)^{-1}T) = \det(I+(\varepsilon_1+\varepsilon_2)S^{-1}T) .$$

In order to prove this identity we introduce $R = S^{-1}T$ and obtain

$$\begin{aligned} &(\mathrm{I} + \varepsilon_1 \mathrm{g}^{-1} \mathrm{T}) \, (\mathrm{I} + \varepsilon_2 (\mathrm{g} + \varepsilon_1 \mathrm{T})^{-1} \mathrm{T}) & = \mathrm{I} + \varepsilon_1 \mathrm{R} \, + \, \varepsilon_2 (\mathrm{I} + \varepsilon_1 \mathrm{R})^{-1} \mathrm{R} \, + \, \varepsilon_1 \varepsilon_2 \mathrm{R} (\mathrm{I} + \varepsilon_1 \mathrm{R})^{-1} \mathrm{R} \\ &= \mathrm{I} + \varepsilon_1 \mathrm{R} + \varepsilon_2 (\mathrm{I} + \varepsilon_1 \mathrm{R})^{-1} \mathrm{R} + \varepsilon_2 (\mathrm{I} + \varepsilon_1 \mathrm{R}) \, (\mathrm{I} + \varepsilon_1 \mathrm{R})^{-1} \mathrm{R} - \varepsilon_2 (\mathrm{I} + \varepsilon_1 \mathrm{R})^{-1} \mathrm{R} \, = \, \mathrm{I} + (\varepsilon_1 + \varepsilon_2) \mathrm{R} \quad . \end{aligned}$$

Now (I.5) follows from the well known formula

$$det(I+\lambda_1)det(I+\lambda_2) = det(I+\lambda_1)(I+\lambda_2)$$

with λ_1 , $\lambda_2 \in \gamma_1$, e.g. see [5].

Formula (0.9) follows from the corollary. Note that

$$\zeta_{\Delta}(z) = (\pi/a)^{-2z}\zeta(2\zeta)$$
 and $\det \Delta_{c} = (\pi/a)e^{-2\zeta^{\dagger}(0)}$

where $\zeta(z)$ is the Riemann ζ - function.

2. Calculation of the partition function

Let us split the interval [x,y] into N equal parts $x=x_0 < x_1 < \ldots < x_N = y$. Consider the finite-dimensional approximation of S

$$\mathbf{s}_{\mathbf{N}} = \int \exp\{-\Sigma_{j=1}^{\mathbf{N}} \mathbf{h}(\mathbf{a}/\mathbf{H}, \xi_{j-1}, \xi_{j})\} d\xi_{1} \dots d\xi_{\mathbf{N}-1}$$

with a=y-x, $\xi_0=\xi$, $\xi_N=\eta$; the definition of the function h is given in the introduction. The invariance of the equation $u_{xx}=u^3$ under the transformation $u(x)+y^{-1}u(y^{-1}x)$ leads us to the homogeneity property

(2.2)
$$h(a/N,\xi_{i-1},\xi_i) = N^3h(a,\xi_{i-1}/N,\xi_i/N) .$$

Therefore

$$s_{N} = N^{N-1} \int \exp\{-N^{3}[h(a,\xi/N,\xi_{1}) + \sum_{j=2}^{N-2} h(a,\xi_{j-1},\xi_{j}) + h(a,\xi_{N-1},n/N)]\} d\xi_{1}...d\xi_{N-1}.$$

We can apply the Laplace method to the integral in (2.3). The function $I(\xi_1,\dots,\xi_{N-1})$ in the square brackets has the unique stationary point $(\xi_1^0,\dots,\xi_{N-1}^0)$

$$\xi_{i}^{o} = N^{-1}U(x,\xi_{i}y,\eta_{i}x+ja/N)$$
.

This point is the point of its strong minimum.

$$s_{N} = (2\pi)^{(N-1)/2} D_{N}^{-1/2} N^{-(N-1)/2} e^{-N^{3} I(\xi_{1}^{0}, \dots, \xi_{N-1}^{0})} (1+O(N^{-1}))$$
,

where

$$D_{N} = \det[I''(\xi_{1}^{\circ}, \dots, \xi_{N-1}^{\circ})].$$

By the homogeneity property (2.2)

$$N^{3}I(\xi_{1}^{0},...,\xi_{N-1}^{0}) = N^{3}h(Na,\xi/N,\eta/N) = h(a,\xi,\eta)$$

and

$$D_{N} = N^{-(N-1)}L_{N} = N^{-(N-1)} \det [J^{**}(\xi_{1}^{\dagger}, \dots, \xi_{N-1}^{\dagger})]$$

with

$$J = \Sigma_{j=1}^{N} h(a/N, \xi_{j-1}, \xi_{j}), \xi_{j}^{1} = N\xi_{j}^{0}$$
.

Finally

$$s_{N} = (2\pi)^{(N-1)/2} L_{N}^{-1/2} e^{-h(\alpha,\xi,\eta)} (1+0(N^{-1}))$$
.

Proposition 1. When N + ...

$$L_{N} = (N^{N}/a^{N-1}) \det(I+3\Delta_{0}^{-1}U^{2}(x,\xi_{IY},\eta_{IZ}))(1+o(1)) .$$

Corollary.

$$\lim_{N\to\infty} (2\pi a)^{(1-N)/2} N^{N/2} s_N = \left[\det(I + 3\Delta_0^{-1} U^2(x,\xi_{jy},\eta_{jz})) \right]^{-1/2}$$

$$e^{-h(y-x,\xi,\eta)} .$$

The expression on the right hand side of the last formula will be called the partition function S.

Proof of Proposition 1. Let $L_{ij} = J_{\xi_{ij}}^{ij}(\xi_{1}^{1},\dots,\xi_{N-1}^{1})$. From the definition of J it follows that

$$\mathbf{L}_{jj} = \frac{a^{2}h}{a\eta^{2}} (\tau, \xi_{j-1}^{1}, \xi_{j}^{1}) + \frac{a^{2}h}{a\xi^{2}} (\tau, \xi_{j}^{1}, \xi_{j+1}^{1}), \tau = a/M \quad ;$$

$$L_{j,j+1} = L_{j+1,j} = \frac{\partial^2 h}{\partial \xi \partial \eta} (\tau, \xi_j^1, \xi_{j+1}^1)$$

$$L_{i,j} = 0$$
 when $|i-j| > 1$.

a). Calculation of $L_{\frac{1}{2}}$. By the definition of the function h

$$L_{jj} = \frac{\partial^2}{\partial \xi^2} \int_{-\tau}^{\tau} \left[\frac{u_z'(\xi_{j-1}^1, \xi, \xi_{j+1}^1, z)^2}{2} + \frac{u^4}{4} \right] dz \Big|_{\xi = \xi_j^1},$$

where u is the solution of the Euler-Lagrange equation $u^{11}=u^3$ for the energy functional, with the conditions $u(-\tau)=\xi_{j-1}^1$, $u(0)=\xi$, $u(\tau)=\xi_{j+1}^1$. By the formula for the second variation

$$L_{11} = \int_{-\tau}^{\tau} [v^{12} + 3u_0^2 v^2] dx$$
,

where $u_0 = u(\xi_{1-1}^1, \xi_{1}^1, \xi_{1+1}^1; z)$, v is the solution of the equation

$$v'' = 3u_0^2 v$$
, $v(\tau) = v(-\tau) = 0$, $v(0) = 1$.

Integrating by parts and taking into account the relation $u_0^{11} = u_0^3$, we obtain

$$L_{jj} = v^{i}(-0) - v^{i}(+0) = -[v^{i}](0)$$

Let us split v into the sum of v_o and w:

$$v_{o}^{"} = 3(\xi_{j}^{1})^{2}v_{o}, w^{"} - 3u_{o}^{2}w = 3[u_{o}^{2} - (\xi_{j}^{1})^{2}]v_{o}, v_{o}(\tau) = v_{o}(-\tau) = w(-\tau) = w(0)$$

$$= w(\tau) = 0, v_{o}(0) = 1.$$

The first equation in (2.5) has the solution

$$v_{\alpha}(z) = \sinh \alpha(\tau - |z|)/\sinh \alpha\tau, \alpha = \sqrt{3} |\xi_{\alpha}^{1}|$$
.

The solution of the second equation in (2.5) has the representation

(2.6)
$$w(z) = 3\Sigma_{j=1}^{\infty} (-1)^{j+1} (3Ku_0^2)^{j} K(u_0^2 - (\xi_j^1)^2) v_0^{-1}$$

where R is the inverse to $-d^2/dx^2$ with zero conditions at the points $\pm \tau$ and 0. It is an integral operator with the kernel

$$K(x,y) = \begin{cases} |x|(\tau - |y|)/\tau & \text{if } |x| < |y|, \text{ sign } x = \text{sign } y \\ |y|(\tau - |x|)/\tau & \text{if } |x| > |y|, \text{ sign } x = \text{sign } y \end{cases}$$

$$0 & \text{if } \text{sign } x \neq \text{sign } y .$$

The series (2.6) is asymptotic with respect to $\tau + 0$ because K is of order τ . Hence $-[w^*](0) \sim (3K(u_O^2 - (\xi_j^1)^2) v_O)^* = -3 \int_0^\tau \frac{(\tau - z) \sin \alpha(\tau - z)}{\sin \alpha\tau} (u_O^2(z) - u_O^2(-z)) dz = 0(\tau^3) .$ Further,

$$-[v^*](0) = 2acthar = \frac{2}{\tau} + \frac{2}{3}a^2\tau + 0(\tau^3)$$
.

Finally,

(2.7)
$$L_{jj} = \frac{2}{\tau} + 2(\xi_{j}^{1})^{2}\tau + O(\tau^{3}) .$$

b). Calculation of Lj,j+1. By definition

$$L_{j,j+1} = \frac{\partial^2}{\partial \xi \partial \eta} \int_0^{\tau} \left[\frac{u_z^*(\xi,\eta_1z)^2}{2} + \frac{u_z^4}{4} \right] dz \Big|_{\xi=\xi_j^1,\eta=\xi_{j+1}^1}$$

with $u(\xi,\eta;z)=U(0,\xi;\tau,\eta;z)$. As above one can easily check that $L_{j,j+1}=v^*(\tau)$, where $v(\tau)$ is the solution of the equation $v^{**}=3u_0^2v$ with the boundary conditions v(0)=1, $v(\tau)=0$; $u_0=u(\xi_j^1,\xi_{j+1}^1;z)$. Splitting v into the sum of $v_0(z)=\sin\alpha(\tau-|z|)/\sin\alpha\tau$ and w(z) we obtain that

$$v_0^{\dagger}(\tau) = -\frac{1}{\tau} + \frac{\alpha^2 \tau}{6} + 0(\tau^3) ,$$

$$v^{\dagger}(\tau) \sim 3 \int_0^{\tau} \frac{z}{\tau} (u^2 - (\xi_j^1)^2) v_0 dz = 0(\tau^2)$$

and finally

(2.8)
$$L_{j,j+1} = -\frac{1}{\tau} + \frac{1}{2} (\xi_j^1)^2 \tau + O(\tau^2) .$$

Now it remains to apply Lemma 1 with

$$F(z) = 30^{2}(x,\xi_{1}y,\eta_{1}x+z), \quad \alpha = 2/3 \text{ and } \beta = 1/3$$

3. The measure du

Let us fix points $x_1 < x_2 < \dots < x_k < x_1 + 2\pi$ on the circle. Consider the function $S(x,\xi) = S(x_1,\xi_1;x_2,\xi_2)S(x_2,\xi_2;x_3,\xi_3)\cdots S(x_k,\xi_k;x_1+2\pi,\xi_1) .$

Proposition 2. Let $x_j^i = (x_1, \dots, \hat{x}_j, \dots, x_k)$, $\xi_j^i = (\xi_1, \dots, \hat{\xi}_j, \dots, \xi_k)$ (the sign ^ means that the corresponding variable is omitted). Then

(3.1)
$$\int S(x,\xi)d\xi_{j} = (2\pi)^{1/2} \sqrt{\frac{(x_{j+1}-x_{j})(x_{j}-x_{j-1})}{x_{j+1}-x_{j-1}}} S(x_{j}^{i},\xi_{j}^{i}) .$$

We assume that $x_0 = x_k - 2\pi$, $x_{k+1} = x_1 + 2\pi$, $\xi_0 = \xi_k$, $\xi_{k+1} = \xi_1$.

Proof. Let all ratios $(x_{m+1}-x_m)/(x_{n+1}-x_n)$ be rational; $x_{m+1}-x_m=x_m$. By Proposition 1

$$\int s(x,\xi) d\xi_{j} = \lim_{m \to \infty} (2\pi)^{k/2} (2\pi)^{(-m/2) \Sigma N_{j}} (m/r)^{(m/2) \Sigma N_{j}}$$

$$\Pi_{V=1}^{k}(x_{V+1}-x_{V})^{1/2} \int \exp\{-Eh(\tau/m,\xi_{V}^{(m)}),\xi_{V+1}^{(m)}\} \frac{d\xi^{(m)}}{d\xi_{1}^{*}},$$

where $x_1 = x_1^{(m)} < x_2^{(m)} < \dots$ is the partition of the circle into equal segments of lenth τ/m . On the other hand

$$S(x_{j}^{i}, \xi_{j}^{i}) = \lim_{n \to \infty} (2\pi)^{(k-1)/2} (2\pi)^{-(n/2)\sum_{i}}$$

$$\pi^k_{\nu=1}(x_{\nu+1}-x_{\nu})^{1/2} \sqrt{\frac{x_{j+1}-x_{j-1}}{(x_{j+1}-x_{j})(x_{j}-x_{j-1})}} \exp\{-\Sigma h(\tau/m,\xi_{\nu}^{(m)},\xi_{\nu+1}^{(m)}\} \frac{d\xi^{(m)}}{d\xi_{j}^{*}} .$$

The realtion (3.1) follows from the last two formulas. In the general case it is valid because of the continuity of both sides.

Corollary 1.

(3.2)
$$\int s(x,\xi) d\xi = \sigma^{-1} (2\pi)^{k/2} \prod_{v=1}^{k} (x_{v+1} - x_v)^{1/2}$$

with some constant o. Actually,

$$\int s(x,\xi) d\xi_1^* = (2\pi)^{(k-2)/2} \pi_{\nu=1}^k (x_{\nu+1} - x_{\nu})^{\frac{1}{2}} s(0,\xi_1;2\pi,\xi_1) .$$

Simple estimates show that

$$\sigma^{-1} = \frac{1}{2\pi} \int S(0,\xi;2\pi,\xi) d\xi < \infty$$
.

Corollary 2. The functions

(3.3)
$$p(x,\xi) = \sigma(2\pi)^{-k/2} \tilde{\pi}(x_{0+1}-x_0)^{-1/2} s(x,\xi)$$

are finite-dimensional densities of a probability measure $d\mu_{4}$. Indeed, they are

continuous and satisfy the agreement and the normalization conditions.

Let dw be a conditional Wiener measure, see [8], in the space of continuous functions which vanish at some fixed point x_0 on the circle: $\delta(f) = f(x_0) = 0$, and $dw = dw \times (2\pi)^{\frac{1}{2}} \exp(-\delta^2/2) d$

is the measure in the space of all continuous functions.

Proposition 3. du, is absolutely continuous with respect to dw and

(3.4)
$$\frac{d\mu_1}{d\tilde{x}}(z) = \sigma(2\pi)^{-\frac{1}{2}} \exp\{-\frac{1}{4} \int z^4(x) dx + \frac{1}{2} z^2(x_0)\}.$$

Proof. Let us choose a function f, a partition $x_0 < x_1 < \ldots < x_k < x_0 + 2\pi$ of the circle and a set

$$M \subset \mathbb{R}^k_{j=0}(f(x_j) \sim \varepsilon, f(x_j) + \varepsilon)$$
.

We assume that $|x_{4+1}-x_4| < \epsilon$, j = 0,...,k. By (3.3)

$$d\mu_1\{M\} = d\mu_1\{u: (u(x_0), \dots, u(x_k)) \in M\}$$

$$= \sigma(2\pi)^{-(k+1)/2} \; \Sigma_{\nu=0}^k (x_{\nu+1} - x_{\nu})^{-J/2} \int_{\mathbb{R}} s(x,\xi) d\xi \quad .$$

Using the definition of h and Theorem 1 we can obtain after simple computations that

$$\mathbf{S}(\mathbf{x},\xi) = \exp\{-\sum_{j=0}^{k} (\xi_{j+1} - \xi_{j})^{2} / 2(\mathbf{x}_{j+1} - \mathbf{x}_{j}) - \frac{1}{4} \int \varepsilon^{4} d\mathbf{x}\} (1 + o(1))$$

when E + 0. Thus

$$d\mu_1\{M\} = \sigma(2\pi)^{-\frac{1}{2}} \exp\{\frac{1}{2} f^2(x_0) - \frac{1}{4} \int f^4 dx\} d\tilde{w}(M)(1+o(1))$$
.

Corollary. The measure $d\mu_{\star}$ has a support in the space Lip^{α} , $\alpha < 1/2$.

For the definition of the $d\mu_2$ we consider functionals λ_4 and λ_5 :

$$\forall = \lambda_0 + \Sigma(\lambda_1 \cos jy + B_v \sin vy)$$
.

Let $M \subset \mathbb{R}^{2N+1}$. Then by definition

$$\begin{split} \mathrm{d}\mu_2 \{ v_1 & (\lambda_0, \dots, \lambda_N, \mu_1, \mu_1, \dots, \mu_N) \in \mathbb{N} \} = \\ &= 2^{-N} \int_{\mathbb{M}} \exp\{-\pi \lambda_0^2 - (\pi/2) \sum_{j=1}^N (\lambda_j^2 + \mu_j^2) \} \mathrm{d}\lambda \mathrm{d}\mu \end{split} .$$

The ${\rm d}\mu_2$ is a realization of the abstract Wiener measure. It has a support in the space of generalized functions

$$\operatorname{Lip}^{\frac{1}{2}-\epsilon} = \operatorname{Const} + \frac{d}{4} \operatorname{Lip}^{\frac{1}{2}-\epsilon}, \; \epsilon > 0 .$$

4. Invariance of the du

Let $\Phi(t)$ be the flow defined by (0.1). First of all we intend to prove its continuity.

Lemma 3. $\Phi(t)$ maps continuously the space $\operatorname{Lip}^{\alpha}(S^1) \times \operatorname{Lip}^{\alpha-1}(S^1)$ into itself, $0 < \alpha < \frac{1}{2}$.

Proof. Consider two Cauchy problems

$$\begin{cases} u_{tt} - u_{xx} + u^3 = 0 \\ u|_{t=0} = u_o(x) \in \text{Lip}^{\alpha}, \ u_t|_{t=0} = v_o(x) \in \text{Lip}^{\alpha-1} \end{cases}$$

and

$$w_{tt} - w_{xx} = 0$$
, $w|_{t=0} = u_0$, $w_t|_{t=0} = v_0$.

If $0 < t < \pi$,

$$w(t,x) = \frac{u_o(x+t)+u_o(x-t)}{2} + \frac{1}{2} \int_{x-t}^{x+t} v_o(y) dy$$
.

Clearly we Lip^{α}, w_t e Lip^{$\alpha-1$} and (w,w_t) depends continuously on (u_0,v_0) . Let r(t,x)=u-v. Then

$$r_{tt} - r_{xx} + (r+w)^3 = 0$$
, $r|_{t=0} = r_t|_{t=0} = 0$

and according to the Duhamel principle

(4.1)
$$r(t,x) = -\int_0^t d\tau \int \frac{\theta(x-y+t-\tau)-\theta(x-y-t+\tau)}{2} \left[r(y,\tau) + w(y,\tau) \right]^3 dy$$

where θ is the Heaviside function. The expression on the right hand side of (4.1) is a contraction operator in a ball in $C(\{0,t\}, \operatorname{Lip}^{\alpha})$ when t is sufficiently small. Therefore (r,r_t) @ $\operatorname{Lip}^{\alpha} \times \operatorname{Lip}^{\alpha-1}$ for sufficiently small t, and hence (u,u_t) @ $\operatorname{Lip}^{\alpha} \times \operatorname{Lip}^{\alpha-1}$. Now the assertion of the lemma follows from the group property of $\theta(t)$ and its invariance under the transformation t * -t.

Now we shall build the finite-dimensional approximation of $\Phi(t)$. Let us divide the circle into 2N+1 equal parts by the points $y_j = 2\pi j/(2N+1)$, j = 0,...,2N. Let ξ_j , η_j , j = 0,...,2N, be some real numbers. We denote by $u_N(\xi,x)$ the solution of the equation $u_{NX} = u^3$ which satisfies the conditions $u_N(\xi,y_4) = \xi_4$;

$$v_N(\eta,x) = A_O + \Sigma_{j=1}^N(A_j \cos jy + B_j \sin jy)$$

is an interpolation trigonometrical polynomial, that is

(4.2)
$$\eta_{ij} = \lambda_{ij} + \Sigma_{ij=1}^{M} (\lambda_{ij} \cos(2\pi i/(2M+1)) + B_{ij} \sin(2\pi i/(2M+1)) .$$

Clearly

(4.3)
$$\Sigma_{j=0}^{M} \eta_{j}^{2} = (2M+1)\Lambda_{0}^{2} + (2M+1)/2 \Sigma_{j=1}^{M} (\Lambda_{j}^{2} + B_{j}^{2})$$
.

Let

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$$H_{H}(\xi,\eta) = \frac{1}{2} \, \xi_{j=0}^{2H} \, \eta_{j}^{2} + \frac{2H+1}{2} \, \int \left[\frac{u_{Hx}^{2}(\xi,x)}{2} + \frac{u_{H}^{4}}{4} \right] dx \quad .$$

By $\theta_{g}(t)$ we denote the Hamiltonian flow with the Hamiltonian H_{g} :

(4.4)
$$\hat{\xi}_{j} = \partial x_{M}/\partial n_{j} = n_{j}; \quad \hat{n}_{j} = -\partial x_{M}/\partial \xi_{j}$$
.

Let $u(x) \in \text{Lip}^{\alpha}$, $v(x) \in \text{Lip}^{\alpha-1}$, $0 < \alpha < 1/2$. For a finite-dimensional approximation of these functions we take vectors

$$\xi^{\mathbb{H}}(u(x)) = (u(y_0), \dots, u(y_{2N}))$$
 and $\eta^{\mathbb{H}}(v(x)) = (\eta_0, \dots, \eta_{2N})$

with η_j defined by (4.2); A and B are Fourier coefficients of v. By r_H we denote the restriction operator $r_H(u,v)=(\xi^H(u),\,\eta^H(v));\,i_H$ is the interpolation operator, $i_H(\xi,\eta)=(u_H(\xi,x),\,v_H(\eta,x)).$

Lemma 4. Let $u(x) \in C^2$ and $v(x) \in C^1$. Then

$$i_{\mathbf{u}} \theta_{\mathbf{u}}(\mathbf{t}) \mathbf{r}_{\mathbf{u}}(\mathbf{u}, \mathbf{v}) + \theta(\mathbf{t})(\mathbf{u}, \mathbf{v})$$
 when $\mathbf{w} + \mathbf{v}$

in the space C1 & C.

Proof. Using the formula of the variation of a functional with a free end, we obtain that

$$\partial H_{M}/\partial \xi_{j} = -\frac{2H+1}{2\pi} \{u_{H}^{*}(\xi,y_{j})\}$$
.

The function u satisfies the equation $u_{H}^{(1)}=u^3=\xi_{j}^3+0(1/N)$. Solving this equation without the term 0(1/N) and estimating the remainder, we can easily obtain that

$$\frac{\partial H_{M}}{\partial \xi_{j}} = -\frac{\xi_{j+1}^{-2\xi_{j}^{+}\xi_{j-1}}}{(2\pi/(2M+1))^{2}} + \xi_{j}^{3} + O(1/M) .$$

Thus (4.4) can be rewritten in the form

(4.4')
$$\xi_{j} = \eta_{j}, \ \eta_{j} = \frac{\xi_{j+1} - 2\xi_{j} + \xi_{j-1}}{(2\pi/(2N+1))^{2}} - \xi_{j}^{3} + O(1/N) .$$

The initial conditions are $\xi_j(0) = u(y_j)$ and $\eta_j(0) = v^{(N)}(y_j)$, where $v^{(N)}$ is the partial sum of the Fourier series of v. We have that $v^{(N)}(y_j) - v(y) = 0(N^{-1+\epsilon})$,

c > 0, uniformly with respect to j because v @ C¹. The system (4.4') with such initial conditions is a difference approximation for the problem

$$u_{ee} - u_{xx} + u^3 = 0$$
, $u(0,x) = u(x)$, $u_e(0,x) = v(x)$.

To finish the proof, we must apply a standard technique, in order to prove the convergence of the solutions of the difference equation to the solution of the differential equation.

Consider a continuous non-linear functional F on $H^{G} \oplus H^{G-1}$ (H is the Sobolev space) such that $\|F(u,v)\| \le 1$. Then

$$\int F(u,v)du = \lim_{N\to\infty} d_N \int F[u_N(\xi,x), v_N(\eta,x)] \exp(-2\pi E_N/(2N+1)) d\xi dAdB .$$

The coordinates (A,B) and n are linearly dependent, therefore dAdB = $c_{\rm H} d\eta$. From the invariance of the measure $d\xi d\eta$ under the flow (4.4) it follows that $d_{\rm H} \int F \left[\Phi_{\rm H} (\tau) (u_{\rm H}(\xi), v_{\rm H}(\eta)) \right] \exp(-2\pi H_{\rm H}/(2H+1)) d\xi dAdB$

(4.5)
$$= d_{in} \int F\{(u_{in}(\xi), v_{in}(\eta)\} \exp(-2\pi R_{in}/(2N+1)) d\xi d\lambda dB .$$

The expression on the right hand side of (4.5) converges to $\int F(u,v) d\mu$ when $N + \infty$. By the same technique as in Lemmas 1 and 3 (the spaces h^{α} and the Duhamel formula) it is easy to verify that $i_{N}^{\alpha}(t)r_{N}$ are uniformly continuous with respect to N as operators from $\text{Lip}^{\alpha} \oplus \text{Lip}^{\alpha-1}$ into $H^{\alpha} \oplus H^{\alpha-1}$, $0 < \alpha < 1/2$. Taking into account Lemma 4,

$$F[\theta_u(t)r_u(u,v)] + F[\theta(t)(u,v)], (u,v) \in Lip^{\alpha-1}$$
.

By the Lebesque theorem, the left hand side in (4.5) converges to $\int F \{\Phi(t)(u,v)\} du$ when $W + \infty$. Therefore

$$\int F(u,v)d\mu = \int F[\Phi(t)(u,v)]d\mu .$$

The last formula means the invariance of du under \$(t).

MOTE: After sending the paper to the publisher, we discovered that the main results of Section 1 - Theorem 1 and the formula (0.9) - were proved simultaneously, independently and by different methods by Mariuss Wodsicki [9].

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Numerical studies of the initial boundary-value problem for the semilinear wave equation

 $u_{tt} - u_{xx} + u^3 = 0$

subject to periodic boundary conditions $u(t,0) = u(t,2\pi)$, $u_{+}(t,0) = u_{+}(t,2\pi)$ and initial conditions $u(0,x) = u_0(x)$, $u_t(0,x) = v_0(x)$, where $u_0(x)$ and $\mathbf{v}_{0}(\mathbf{x})$ satisfy the same periodic conditions, suggest that solutions ultimately

ABSTRACT (continued)

return to a neighborhood of the initial state $u_0(x)$, $v_0(x)$ after undergoing a possibly chaotic evolution.

In this paper an appropriate abstract space is considered. In this space a finite measure is constructed. This measure is invariant under the flow generated by the Hamiltonian system which corresponds to the original equation. This enables one to verify the above "returning" property.